

FIXED POINT THEOREMS IN DISLOCATED QUASI METRIC SPACES  
USING THE NOTION OF A- CONTRACTIONSK. P. R. Sastry<sup>1</sup>, S. Kalesha Vali<sup>2</sup>, Ch. Srinivasa Rao<sup>3</sup> and M. A. Rahamatulla<sup>4\*</sup><sup>1</sup>8-28-8/1, Tamil Street, Chinna Waltair, Visakhapatnam - 530 017, India<sup>2</sup>Department of Mathematics, GITAM University, Visakhapatnam - 530 045, India<sup>3</sup>Department of Mathematics, Mrs. A.V.N. College, Visakhapatnam -530 001, India<sup>4</sup>Department of Mathematics, Al -Aman College of Engineering, Visakhapatnam – 531 173, India

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## ABSTRACT

A fixed point theorem for a self map  $T$  (not necessarily continuous) on a complete  $dq$ - metric space is proved. Incidentally, we show that a result of Rajesh. S., Ansari.Z.K. and Manish Sharma [12] in its revised form (Theorem 2.1) is not valid through an example. We also extend a fixed point theorem for two self maps on a dislocated metric space of Rajesh.et.al [12] to dislocated quasi metric spaces.

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**Key words:** Dislocated metric space,  $dq$ -metric space, contractive condition, fixed point, A – contraction.

## 0. INTRODUCTION

The concept of dislocated metrics was studied under the name of metric domains in the context of domain theory in [2]. As a generalization of metrics where the self distance for any point need not to be equal to zero, Hitzler [6] and Hitzler and Seda [7], introduced the notion of dislocated metric spaces and generalized the celebrated Banach contraction principle in such spaces. These metrics play a very important role not only in topology but also in other branches of Science involving mathematics especially in logic programming and electronic engineering.

Zeyada.et.al [15] initiated the concept of dislocated quasi metric space and generalized the result of Hitzler and Seda [7] in dislocated quasi metric spaces. Recently, the study in such spaces is followed by Isufati [8] and C. T. Aage and J. N. Salunke [1]. In [8], the author proved some fixed point results in dislocated quasi metric spaces involving continuous contraction mappings which exist in the literature of usual complete metric space. In [1] the authors proved Kannan's [10] fixed point theorem and Lj. B. Ćirić's [5] generalized contraction on complete metric spaces in the setting of dislocated quasi metric spaces. On the other hand, it is well known that Banach contraction principle is a pivotal result in the metric fixed point theory. This principle has been generalized by various authors by putting different types of contractive conditions. In the sequel, D.S. Jaggi [9] proved a fixed point theorem using rational type of contractive condition which generalized the Banach contraction principle in complete metric spaces.

In 2008 Akram.et.al [3] introduced a larger class of contractions, called A- contractions and showed that the class of A- contractions is a proper super class of Kannan's [10], Khan's [11], Bianchini's [4] and S. Reich [13], type contractions. Also, the authors proved fixed point theorems for A-contraction in complete metric spaces. Rajesh Srivastava.et.al [12] presented a version of D.S. Jaggi's [9] fixed point theorem in the context of dislocated quasi metric spaces. Further a common fixed point theorem is also obtained in complete dislocated metric space, using the notion of A-contraction in Rajesh.et.al [12].

In this paper, we observe that Theorem 3.1 of Rajesh.et.al [12] is not meaningful and provide a revised statement to make this theorem meaningful. Further we prove a fixed point theorem for a self map on a complete dislocated quasi metric space, satisfying a condition similar to the one in Rajesh.et.al [12]. We also extend a fixed point theorem for a A- contraction pair on a dislocated metric space (Theorem 3.7 of Rajesh.et.al [12]) to dislocated quasi metric spaces.

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## 1. PRELIMINARIES

**Definition 1.1:** [14] Sastry. K.P.R., Vali. S.K., SrinivasaRao. Ch. and Rahamatulla. M.A. [14] Let  $X$  be a non-empty set and let  $d: X \times X \rightarrow [0, \infty)$  be a function, called a distance function, satisfying one or more of

$$\begin{aligned} d_1 &: d_5. \\ d_1 &: d(x, x) = 0 \quad \forall x \in X, \\ d_2 &: d(x, y) = d(y, x) = 0 \implies x = y \quad \forall x, y \in X, \\ d_3 &: d(x, y) = d(y, x) \quad \forall x, y \in X, \\ d_4 &: d(x, y) \leq d(x, z) + d(z, y) \quad \forall x, y, z \in X, \\ d_5 &: d(x, y) \leq \max\{d(x, z), d(z, y)\} \quad \forall x, y, z \in X. \end{aligned}$$

- (i) If  $d$  satisfies  $d_2, d_3$  and  $d_4$  then  $d$  is called a dislocated metric and  $(X, d)$  is called a dislocated metric space.
- (ii) If  $d$  satisfies  $d_1, d_2$  and  $d_4$  then  $d$  is called a quasi metric and  $(X, d)$  is called a quasi metric space.
- (iii) If  $d$  satisfies  $d_2$  and  $d_4$  then  $d$  is called a dislocated quasi metric (or)dq-metric and  $(X, d)$  is called a dq-metric space.
- (iv) If  $d$  satisfies  $d_1, d_2, d_3$  and  $d_4$  then  $d$  is called a metric and  $(X, d)$  is called a metric space.

**Definition 1.2:** A sequence  $\{x_n\}$  in a dq-metric space  $(X, d)$  is called Cauchy if to  $\epsilon > 0$ , there exists  $n_0 \in N$  such that for all  $m, n \geq n_0$ ,  $d(x_m, x_n) < \epsilon$ .

**Definition 1.3:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] A sequence  $\{x_n\}$  in a dislocated quasi metric space  $(X, d)$  is said to be dislocated quasi converges (or) dq - converges to  $x$ , if

$$\lim_{n \rightarrow \infty} d(x_n, x) = \lim_{n \rightarrow \infty} d(x, x_n) = 0.$$

In this case  $x$  is called a dq – limit of  $\{x_n\}$  and we write  $x_n \rightarrow x$ .

**Proposition 1.4:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] Every convergent sequence is a dq- metric space is Cauchy.

**Definition 1.5:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] A dq – metric space  $(X, d)$  is complete, if every Cauchy sequence in it is dq – convergent.

**Lemma 1.6:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] Every subsequence of a dq – convergent sequence to a point  $x_0$  is dq – convergent to  $x_0$ .

**Definition 1.7:** Let  $(X, d), (Y, d')$  be dq - metric spaces. Suppose  $f: X \rightarrow Y$ , we say that  $f$  is continuous, if

$$\{x_n\} \rightarrow x \implies f x_n \rightarrow f x \text{ in } Y.$$

**Definition 1.8:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] Let  $(X, d)$  be a dq- metric space. A mapping  $f: X \rightarrow X$  is called a contraction if there exists  $0 \leq \lambda < 1$  such that

$$d(f(x), f(y)) \leq \lambda d(x, y) \text{ for all } x, y \in X.$$

**Lemma 1.9:** eyada.F.M. Hassan.G.H. and Ahmed.M.A. [15] Let  $(X, d)$  be a dq- metric space. If  $f: X \rightarrow X$  is a contraction function, then  $f^n(x_0)$  is a Cauchy sequence for each  $x_0 \in X$ .

**Lemma 1.10:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] dq – limits in a dq – metric space are unique.

**Theorem 1.11:** Zeyada.F.M., Hassan.G.H. and Ahmed.M.A. [15] Let  $(X, d)$  be a complete dq - metric space and let  $f: X \rightarrow X$  be a continuous contraction function. Then  $f$  has a unique fixed point.

### RAJESH.S. ANSARI.Z.K. AND MANISH SHARMA [12] CLAIMED THE FOLLOWING RESULT

**Theorem 1.12 (Rajesh's., Ansari.Z.K. and Manish Sharma [12], Theorem 3.1)** Let  $T$  be a continuous self map defined on a complete metric space  $(X, d)$ . Further let  $T$  satisfy the following contraction condition

$$d(Tx, Ty) \leq \alpha \frac{d(x, Tx)d(y, Ty)}{d(x, y)} + \beta d(x, y) \tag{1.12.1}$$

for all  $x, y \in X, x \neq y$  and for some  $\alpha, \beta \in [0, 1)$  with  $\alpha + \beta < 1$ , Then  $T$  has unique fixed point.

**Note 1.13:** Condition (1.12.1) is meaningless if  $d(x, x) = 0$ . Also we note that  $x \neq y$  and  $d(x, y) = 0$  may happen in a dq - metric space.

Hence a revised statement of Theorem (1.12) to make this meaningful is given in Theorem (2.1).

**Definition 1.14:** Akram.M. Zafar.A.A. and Siddiqui.A.A. [3] A self map  $T$  on a metric space  $(X, d)$  satisfying

$$d(Tx, Ty) \leq \alpha \max \left\{ \begin{array}{l} d(x, Tx) + d(y, Ty), \\ d(y, Ty) + d(x, y), \\ d(x, Tx) + d(x, y) \end{array} \right\} \quad (1.14.1)$$

for all  $x, y \in X$  and some  $\alpha, \beta \in [0, \frac{1}{2})$  is called a A- contraction.

**Note 1.15:** The notion of A-contraction can be extended in a natural way to dq – metric spaces also with metric space replaced by dq – metric space. We use this notion of A - contraction in dq – metric space in the next section.

## 2 . MAIN RESULTS

**WE REVISE THE STATEMENT OF THEOREM (1.12) AS FOLLOWS, TO MAKE IT MEANINGFUL.**

**Theorem 2.1:** Let  $T$  be a continuous self mapping defined on a complete dq-metric space  $(X, d)$ . Further let  $T$  satisfy the following contractive condition

$$d(Tx, Ty) \leq \alpha \frac{d(x, Tx)d(y, Ty)}{d(x, y)} + \beta d(x, y) \quad (2.1.1)$$

for all  $x, y \in X$ , whenever  $d(x, y) \neq 0$ .

Then  $T$  has a unique fixed point.

**WE OBSERVE THAT THEOREM 2.1 IS NOT VALID IN VIEW OF THE FOLLOWING EXAMPLE.**

**Example 2.2:** Let  $X = \{0,1\}$ , define  $d(0,0) = 0, d(0,1) = 1, d(1,0) = 0, d(1,1) = 0$ , and define  $T : X \rightarrow X$  as  $T0 = 1$  and  $T1 = 0$ . Then  $(X, d)$  is a complete dq- metric space,  $T$  satisfies (2.1.1) and  $T$  has no fixed Point.

**NOW WE PROVE A THEOREM, SIMILAR TO THEOREM 2.1 WITHOUT ASSUMING CONTINUITY OF T WHICH HOLDS GOOD IN A COMPLETE DQ – METRIC SPACE.**

**Theorem 2.3:** Let  $T$  be a self map defined on a complete dq-metric space  $(X, d)$ , let  $T$  satisfy the condition

$$d(Tx, Ty) \leq \alpha \frac{d(x, Tx)d(y, Ty)}{\max\{d(x, y), d(y, x)\}} + \beta d(x, y) \quad (2.3.1)$$

for all  $x, y \in X$ , whenever  $d(x, y) \neq 0$  (or)  $d(y, x) \neq 0$ .

That is  $d(x, y) + d(y, x) \neq 0$ , where  $\alpha, \beta$  are non – negitive and  $\alpha + \beta < 1$ . Then  $T$  has a unique fixed point.

**Proof:** Suppose

$\max\{d(x, Tx), d(Tx, x)\} \neq 0$ . Put  $y = Tx$  in (2.3.1). We get

$$\begin{aligned} d(Tx, TTx) &\leq \alpha \frac{d(x, Tx)d(Tx, TTx)}{\max\{d(x, Tx), d(Tx, x)\}} + \beta d(x, Tx) \\ &\leq \alpha d(Tx, TTx) + \beta d(x, Tx) \end{aligned}$$

$$\therefore d(Tx, TTx) \leq \frac{\beta}{1-\alpha} d(x, Tx) \leq \frac{\beta}{1-\alpha} \max\{d(x, Tx), d(Tx, x)\}$$

Similarly we can show that (by replacing  $x$  with  $Tx$  and  $y$  with  $x$  in (2.3.1))

$$d(TTx, Tx) \leq \frac{\beta}{1-\alpha} \max\{d(x, Tx), d(Tx, x)\}$$

$$\therefore \max \{d(Tx, TTx), d(TTx, Tx)\} \leq \frac{\beta}{1-\alpha} \max\{d(x, Tx), d(Tx, x)\} \quad (2.3.2)$$

Let  $x_0 \in X$ . Define the sequence  $\{x_n\}$  iteratively as follows:

$$x_1 = Tx_0, x_2 = Tx_1, \dots, x_{n+1} = Tx_n.$$

Suppose, for some  $n$ ,  $x_{n+1} = x_n$ . Then  $Tx_n = x_{n+1} = x_n$ , so that  $x_n$  is a fixed point of  $T$ .

Now suppose that  $x_n \neq x_{n+1}$  for  $n = 0, 1, 2, \dots$ . Then, clearly

$$\max\{d(x_{n-1}, x_n), d(x_n, x_{n-1})\} \neq 0, \text{ for } n = 1, 2, 3, \dots$$

$$\text{Hence, by (2.3.2) } \max\{d(x_n, x_{n+1}), d(x_{n+1}, x_n)\} \leq \frac{\beta}{1-\alpha} \max\{d(x_{n+1}, x_n), d(x_n, x_{n+1})\}$$

Since  $\frac{\beta}{1-\alpha} < 1$ , this shows that

$$\leq \left(\frac{\beta}{1-\alpha}\right)^n \max\{d(x_0, x_1), d(x_1, x_0)\} \text{ and hence the sequence } \{x_n\} \text{ is a Cauchy sequence.}$$

$$\therefore x_n \rightarrow u \text{ for some } u \in X \quad (2.3.3)$$

**Case (i):** Suppose  $\max\{d(x_n, u), d(u, x_n)\} \neq 0$  for large  $n$ . Then, by (2.3.1),

$$\begin{aligned} d(x_{n+1}, Tu) &= d(Tx_n, Tu) \\ &\leq \alpha \frac{d(x_n, Tx_n)d(u, Tu)}{\max\{d(x_n, u), d(u, x_n)\}} + \beta d(x_n, u), \text{ if } x_n \neq u \text{ for large } n. \\ &\rightarrow 0 \text{ as } n \rightarrow \infty. \end{aligned}$$

Similarly

$$d(Tu, x_{n+1}) \rightarrow 0 \text{ as } n \rightarrow \infty.$$

Hence  $x_{n+1} \rightarrow Tu$

But  $x_{n+1} \rightarrow u$  (by (2.3.3))

Consequently by lemma 1.10,  $Tu = u$ .

**Case (ii):** Suppose  $x_n = u$  for infinitely many  $n$ . Then for such  $n$ ,  $x_{n+1} = Tx_n = Tu$ . Then

$$d(x_n, x_{n+1}) < \epsilon \text{ and } d(x_{n+1}, x_n) < \epsilon \text{ for } n \geq N. \text{ and hence } d(u, Tu) < \epsilon \text{ and } d(Tu, u) < \epsilon.$$

This being true for every  $\epsilon > 0$  follows that

$$d(u, Tu) = 0 = d(Tu, u)$$

Hence  $Tu = u$ . Thus  $u$  is a fixed point of  $T$ .

### UNIQUENESS

First suppose that  $Tx = x$ . Then  $d(x, x) \neq 0$ .

$$\begin{aligned} \Rightarrow d(x, x) &= d(Tx, Tx) \leq \alpha \frac{d(x, x)d(x, x)}{\max\{d(x, x), d(x, x)\}} + \beta d(x, x) \\ &\leq \alpha d(x, x) + \beta d(x, x) \\ &\leq (\alpha + \beta)d(x, x) \\ &< d(x, x), \text{ a contradiction,} \end{aligned}$$

$$\therefore d(x, x) = 0, \text{ if } x \text{ is a fixed point of } T \quad (2.3.4)$$

Suppose that  $x$  and  $y$  in  $X$  are two distinct fixed point of  $T$ . That is  $Tx = x$  and  $Ty = y$ .

Then  $\max\{d(x, y), d(y, x)\} \neq 0$  and hence by (2.3.1), we have

$$\begin{aligned} d(x, y) = d(Tx, Ty) &\leq \alpha \frac{d(x, Tx)d(y, Ty)}{\max\{d(x, y), d(y, x)\}} + \beta d(x, y) \\ &= \beta d(x, y) \quad (\text{by (2.3.4)}) \end{aligned}$$

$$\therefore (1 - \beta)d(x, y) \leq 0$$

$$\therefore d(x, y) = 0, \text{ Similarly } d(y, x) = 0.$$

$$\therefore d(x, y) = d(y, x) = 0 \Rightarrow x = y.$$

Thus fixed point of  $T$  is unique. Thus the proof completes.

**Corollary 2.4:** Let  $T$  be a continuous self mapping defined on a complete dq – metric space  $(X, d)$ . Further let  $T$  satisfy the contractive condition

$$d(Tx, Ty) \leq \alpha \frac{d(x, Tx)d(y, Ty)}{d(x, y) + d(y, x)} + \beta d(x, y) \tag{2.4.1}$$

for all  $x, y \in X, x \neq y$  and for some  $\alpha, \beta \in [0, 1)$  with  $\alpha + \beta < 1$ . Then  $T$  has a unique fixed point.

**Proof:** Since  $\max\{d(x, y), d(y, x)\} \leq d(x, y) + d(y, x)$ , it follows that (2.4.1)  $\Rightarrow$  (2.3.1)

Hence corollary 2.4 follows from Theorem 2.3. In continuation of Note 1.15, we introduce the notion of A – contraction for two maps on a complete dislocated quasi metric space as follows:

**Definition 2.5:** Let  $(X, d)$  be a complete dislocated quasi metric space. Suppose  $S, T : X \rightarrow X$  are self maps satisfying

$$\max\{d(Sx, Ty), d(Ty, Sx)\} \leq \alpha \max \left\{ \begin{array}{l} d(x, Tx) + d(y, Ty), \\ d(y, Ty) + d(x, y), \\ d(x, Tx) + d(x, y) \end{array} \right\} \text{ for all } x, y \in X \text{ and for some } \alpha \in [0, \frac{1}{2}).$$

Then  $(S, T)$  is called A- contraction.

**NOW WE EXTEND THE RESULT (THEOREM 3.7) OF [12] TO DISLOCATED QUASI METRIC SPACES AS FOLLOWS.**

**Theorem 2.6:** Let  $(X, d)$  be a complete dislocated quasi metric space. Let  $S, T : X \rightarrow X$  be continuous self mapping. Suppose  $(S, T)$  is a A- contraction. Then  $S$  and  $T$  have unique common fixed point.

**Proof:** Let  $x_0 \in X$ . Define the sequence  $\{x_n\}$  by  $x_1 = Sx_0, x_2 = Tx_1, \dots, x_{2n} = Tx_{2n-1}, \dots, x_{2n+1} = Sx_{2n}, \dots$ . Now, for some  $\alpha \in [0, \frac{1}{2})$ ,

$$\begin{aligned} d(Sx, TSx) &\leq \alpha \max \left\{ \begin{array}{l} d(x, Sx) + d(Sx, TSx), \\ d(Sx, TSx) + d(x, Sx), \\ d(x, Sx) + d(x, Sx) \end{array} \right\} \\ &= \alpha \max\{d(x, Sx) + d(Sx, TSx), 2d(x, Sx)\} \\ &= \alpha \{d(x, Sx) + d(Sx, TSx)\} \text{ (or) } , 2\alpha d(x, Sx) \end{aligned}$$

$$\therefore d(Sx, TSx) \leq \frac{\alpha}{1-\alpha} d(x, Sx) \text{ (or) } 2\alpha d(x, Sx)$$

$$\therefore d(Sx, TSx) \leq 2\alpha d(x, Sx)$$

Now writing  $x = x_{2n}$ , we get

$$d(Sx_{2n}, TSx_{2n}) \leq 2\alpha d(x_{2n}, Sx_{2n})$$

$$\text{i.e } d(x_{2n+1}, x_{2n+2}) \leq 2\alpha d(x_{2n}, x_{2n+1})$$

$$\therefore d(x_{2n+1}, x_{2n+2}) \leq Kd(x_{2n}, x_{2n+1}), \text{ where } K = 2\alpha < 1$$

Similarly, we can show that

$$d(x_{2n}, x_{2n+1}) \leq Kd(x_{2n-1}, x_{2n})$$

$$\text{Hence } d(x_{n+1}, x_{n+2}) \leq Kd(x_{n-1}, x_n) \text{ for } n = 1, 2, 3, \dots$$

Consequently, we get

$$d(x_{n+1}, x_{n+2}) \leq K^n d(x_0, x_1)$$

$$\text{Since } 0 \leq K < 1, \text{ as } n \rightarrow \infty, K^n \rightarrow 0.$$

Thus the sequence  $\{x_n\}$  is a Cauchy sequence in the complete dislocated quasi metric space  $X$ . Therefore there exists a point  $u \in X$  such that  $x_n \rightarrow u$ .

$$\therefore \text{The subsequence } \{Sx_{2n}\} \rightarrow u \text{ and } \{Tx_{2n+1}\} \rightarrow u.$$

Since  $S$  and  $T$  are continuous, so we have  $Su = u$  and  $Tu = u$ .

$\therefore u$  is a common fixed point of  $S$  and  $T$ .

#### UNIQUENESS

Let  $u$  and  $v$  be common fixed points of  $S$  and  $T$  Then by (1.14.1)

$$d(u, u) = d(Su, Tu) \leq \alpha \max \left\{ \begin{array}{l} d(u, u) + d(u, u), \\ d(u, u) + d(u, u), \\ d(u, u) + d(u, u) \end{array} \right\}$$

$$\therefore d(u, u) \leq 2\alpha d(u, u). \text{ Since } \alpha < \frac{1}{2}, \text{ this shows that } d(u, u) = 0,$$

Similarly,  $d(v, v) = 0$ .

$$\text{Now } d(u, v) = d(Su, Tv) \leq \alpha \max \left\{ \begin{array}{l} d(u, u) + d(v, v), \\ d(v, v) + d(u, v), \\ d(u, u) + d(u, v) \end{array} \right\}$$

$$= \alpha d(u, v). \text{ So that } d(u, v) = 0.$$

Similarly we have  $d(v, u) = 0$  and so  $u = v$ .

Hence  $S$  and  $T$  have a unique common fixed point.

Thus the proof completes.

**Corollary 2.7 (Theorem 3.7 of [12]):** Let  $(X, d)$  be a complete dislocated metric space. Let  $S, T : X \rightarrow X$  be continuous mappings satisfying:

$$d(Sx, Ty) \leq \alpha \max \left\{ \begin{array}{l} d(x, Sx) + d(y, Ty), \\ d(y, Ty) + d(x, y), \\ d(x, Sx) + d(x, y) \end{array} \right\} \text{ for all } x, y \in X \text{ and for some } \alpha \in [0, \frac{1}{2}).$$

Then  $S$  and  $T$  have common fixed point.

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